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KEY=PREDICTIVE - OSCAR WOOD

Model Predictive Control in the Process Industry Springer Science & Business Media *Model Predictive Control is an important technique used in the process control industries. It has developed considerably in the last few years, because it is the most general way of posing the process control problem in the time domain. The Model Predictive Control formulation integrates optimal control, stochastic control, control of processes with dead time, multivariable control and future references. The finite control horizon makes it possible to handle constraints and non linear processes in general which are frequently found in industry. Focusing on implementation issues for Model Predictive Controllers in industry, it fills the gap between the empirical way practitioners use control algorithms and the sometimes abstractly formulated techniques developed by researchers. The text is firmly based on material from lectures given to senior undergraduate and graduate students and articles written by the authors. **Nonlinear Model Predictive Control Theory and Algorithms** Springer This book offers readers a thorough and rigorous introduction to nonlinear model predictive control (NMPC) for discrete-time and sampled-data systems. NMPC schemes with and without stabilizing terminal constraints are detailed, and intuitive examples illustrate the performance of different NMPC variants. NMPC is interpreted as an approximation of infinite-horizon optimal control so that important properties like closed-loop stability, inverse optimality and suboptimality can be derived in a uniform manner. These results are complemented by discussions of feasibility and robustness. An introduction to nonlinear optimal control algorithms yields essential insights into how the nonlinear optimization routine—the core of any nonlinear model predictive controller—works. Accompanying software in MATLAB® and C++ (downloadable from extras.springer.com/), together with an explanatory appendix in the book itself, enables readers to perform computer experiments exploring the possibilities and limitations of NMPC. The second edition has been substantially rewritten, edited and updated to reflect the significant advances that have been made since the publication of its predecessor, including:*

- a new chapter on economic NMPC relaxing the assumption that the running cost penalizes the distance to a pre-defined equilibrium;
- a new chapter on distributed NMPC discussing methods which facilitate the control of large-scale systems by splitting up the optimization into smaller subproblems;
- an extended discussion of stability and performance using approximate updates rather than full optimization;
- replacement of the pivotal sufficient condition for stability without stabilizing terminal conditions with a weaker alternative and inclusion of an alternative and much simpler proof in the analysis; and
- further variations and extensions in response to suggestions from readers of the first edition.

Though primarily aimed at academic researchers and practitioners working in control and optimization, the text is self-contained, featuring background material on infinite-horizon optimal control and Lyapunov stability theory that also makes it accessible for graduate students in control engineering and applied mathematics. **Model Predictive Control Classical, Robust and Stochastic** Springer For the first time, a textbook that brings together classical predictive control with treatment of up-to-date robust and stochastic techniques. Model Predictive Control describes the development of tractable algorithms for uncertain, stochastic, constrained systems. The starting point is classical predictive control and the appropriate formulation of performance objectives and constraints to provide guarantees of closed-loop stability and performance. Moving on to robust predictive control, the text explains how similar guarantees may be obtained for cases in which the model describing the system dynamics is subject to additive disturbances and parametric uncertainties. Open- and closed-loop optimization are considered and the state of the art in computationally tractable methods based on uncertainty tubes presented for systems with additive model uncertainty. Finally, the tube framework is also applied to model predictive control problems involving hard or probabilistic constraints for the cases of multiplicative and stochastic model uncertainty. The book provides: extensive use of illustrative examples; sample problems; and discussion of novel control applications such as resource allocation for sustainable development and turbine-blade control for maximized power capture with simultaneously reduced risk of turbulence-induced damage. Graduate students pursuing courses in model predictive control or more generally in advanced or process control and senior undergraduates in need of a specialized treatment will find Model Predictive Control an invaluable guide to the state of the art in this important subject. For the instructor it provides an authoritative resource for the construction of courses. **Distributed Model Predictive Control Made Easy** Springer Science & Business Media The rapid evolution of computer science, communication, and information technology has enabled the application of control techniques to systems beyond the possibilities of control theory just a decade ago. Critical infrastructures such as electricity, water, traffic and intermodal transport networks are now in the scope of control engineers. The sheer size of such large-scale systems requires the adoption of advanced distributed control approaches. Distributed model predictive control (MPC) is one of the promising control methodologies for control of such systems. This book provides a state-of-the-art overview of distributed MPC approaches, while at the same time making clear directions of research that deserve more attention. The core and rationale of 35 approaches are carefully explained. Moreover, detailed step-by-step algorithmic descriptions of each approach are provided. These features make the book a comprehensive guide both for those seeking an introduction to distributed MPC as well as for those who want to gain a deeper insight in the wide range of distributed MPC techniques available. **Nonlinear Model Predictive Control** Birkhäuser During the past decade model predictive control (MPC), also referred to as receding horizon control or moving horizon control, has become the preferred control strategy for quite a number of industrial processes. There have been many significant advances in this area over the past years, one of the most important ones being its extension to nonlinear systems. This book gives an up-to-date assessment of the current state of the art in the new field of nonlinear model predictive control (NMPC). The main topic areas that appear to be of central importance for NMPC are covered, namely receding horizon control theory, modeling for NMPC, computational aspects of on-line optimization and application issues. The book consists of selected papers presented at the International Symposium on Nonlinear Model Predictive Control - Assessment and Future Directions, which took place from June 3 to 5, 1998, in Ascona, Switzerland. The book is geared towards researchers and practitioners in the area of control engineering and control theory. It is also suited for postgraduate students as the book contains several overview articles that give a tutorial introduction into the various aspects of nonlinear model predictive control, including systems theory, computations, modeling and applications. **Receding Horizon Control Model Predictive Control for State Models** Springer Science & Business Media Easy-to-follow learning structure makes absorption of advanced material as pain-free as possible Introduces complete theories for stability and cost monotonicity for constrained and non-linear systems as well as for linear systems In co-ordination with MATLAB® files available from springeronline.com, exercises and examples give the student more practice in the predictive control and filtering techniques presented **Model-Based Predictive Control A Practical Approach** CRC Press Model Predictive Control (MPC) has become a widely used methodology across all engineering disciplines, yet there are few books which study this approach. Until now, no book has addressed in detail all key issues in the field including apriori stability and robust stability results. Engineers and MPC researchers now have a volume that provides a complete overview of the theory and practice of MPC as it relates to process and control engineering. Model-Based Predictive Control, A Practical Approach, analyzes predictive control from its base mathematical foundation, but delivers the subject matter in a readable, intuitive style. The author writes in layman's terms, avoiding jargon and using a style that relies upon personal insight into practical applications. This detailed introduction to predictive control introduces basic MPC concepts and demonstrates how they are applied in the design and control of systems, experiments, and industrial processes. The text outlines how to model, provide robustness, handle constraints, ensure feasibility, and guarantee stability. It also details options in regard to algorithms, models, and complexity vs. performance issues. **Practical Design and Application of Model Predictive Control MPC for MATLAB® and Simulink® Users** Butterworth-Heinemann Practical Design and Application of Model Predictive Control is a self-learning resource on how to design, tune and deploy an MPC using MATLAB® and Simulink®. This reference is one of the most detailed publications on how to design and tune MPC controllers. Examples presented range from double-Mass spring system, ship heading and speed control, robustness analysis through Monte-Carlo simulations, photovoltaic optimal control, and energy management of power-split and air-handling control. Readers will also learn how to embed the designed MPC controller in a real-time platform such as Arduino®. The selected problems are nonlinear and challenging, and thus serve as an excellent experimental, dynamic system to show the reader the capability of MPC. The step-by-step solutions of the problems are thoroughly documented to allow the reader to easily replicate the results. Furthermore, the MATLAB® and Simulink® codes for the solutions are available for free download. Readers can connect with the authors through the dedicated website which includes additional free resources at www.practicalmpc.com. Illustrates how to design, tune and deploy MPC for projects in a quick manner Demonstrates a variety of applications that are solved using MATLAB® and Simulink® Bridges the gap in providing a number of realistic problems with very hands-on training Provides MATLAB® and Simulink® code solutions. This includes nonlinear plant models that the reader can use for other projects and research work Presents application problems with solutions to help reinforce the information learned **Handbook of Model Predictive Control** Springer Recent developments in model-predictive control promise remarkable opportunities for designing multi-input, multi-output control systems and improving the control of single-input, single-output systems. This volume provides a definitive survey of the latest model-predictive control methods available to engineers and scientists today. The initial set of chapters present various methods for managing uncertainty in systems, including stochastic model-predictive control. With the advent of affordable and fast computation, control engineers now need to think about using “computationally intensive controls,” so the second part of this book addresses the solution of optimization problems in “real” time for model-predictive control. The theory and applications of control theory often influence each other, so the last section of Handbook of Model Predictive Control rounds out the book with representative applications to automobiles, healthcare, robotics, and finance. The chapters in this volume will be useful to working engineers, scientists, and mathematicians, as well as students and faculty interested in the progression of control theory. Future developments in MPC will no doubt build from concepts demonstrated in this book and anyone with an interest in MPC will find fruitful information and suggestions for additional reading. **Predictive Control for Linear and Hybrid Systems** Cambridge University Press With a simple approach that includes real-time applications and algorithms, this book covers the theory of model predictive control (MPC). **Model Predictive Control Theory, Computation, and Design Model Predictive Control System Design and Implementation Using MATLAB®** Springer Science & Business Media Model Predictive Control System Design and Implementation Using MATLAB® proposes methods for design and implementation of MPC systems using basis functions that confer the following advantages: - continuous- and discrete-time MPC problems solved in similar design frameworks; - a parsimonious parametric representation of the control trajectory gives rise to computationally efficient algorithms and better on-line performance; and - a more general discrete-time representation of MPC design that becomes identical to the traditional approach for an appropriate choice of parameters. After the theoretical presentation, coverage is given to three industrial applications. The subject of quadratic programming, often associated with the core optimization algorithms of MPC is also introduced and explained. The technical contents of this book is mainly based on advances in MPC using state-space models and basis functions. This volume includes numerous analytical examples and problems and MATLAB® programs and exercises. **Automotive Model Predictive Control Models, Methods and Applications** Springer Science & Business Media Automotive control has developed over the decades from an auxiliary te- nology to a key element without which the actual performances, emission, safety and consumption targets could not be met. Accordingly, automotive control has been increasing its authority and responsibility - at the price of complexity and di?cult tuning. The progressive evolution has been mainly ledby speci?capplicationsandshorttermtargets,withthe consequencethat automotive control is to a very large extent more heuristic than

systematic. Product requirements are still increasing and new challenges are coming from potentially huge markets like India and China, and against this background there is wide consensus both in the industry and academia that the current state is not satisfactory. Model-based control could be an approach to improve performance while reducing development and tuning times and possibly costs. Model predictive control is a kind of model-based control design approach which has experienced a growing success since the middle of the 1980s for "slow" complex plants, in particular of the chemical and process industry. In the last decades, several developments have allowed using these methods also for "fast" systems and this has supported a growing interest in its use also for automotive applications, with several promising results reported. Still there is no consensus on whether model predictive control with its high requirements on model quality and on computational power is a sensible choice for automotive control. **Model Predictive Control** Springer Science & Business Media The second edition of "Model Predictive Control" provides a thorough introduction to theoretical and practical aspects of the most commonly used MPC strategies. It bridges the gap between the powerful but often abstract techniques of control researchers and the more empirical approach of practitioners. The book demonstrates that a powerful technique does not always require complex control algorithms. Many new exercises and examples have also been added throughout. Solutions available for download from the authors' website save the tutor time and enable the student to follow results more closely even when the tutor isn't present. **Dynamic Modeling, Predictive Control and Performance Monitoring** Springer Science & Business Media A typical design procedure for model predictive control or control performance monitoring consists of: 1. identification of a parametric or nonparametric model; 2. derivation of the output predictor from the model; 3. design of the control law or calculation of performance indices according to the predictor. Both design problems need an explicit model form and both require this three-step design procedure. Can this design procedure be simplified? Can an explicit model be avoided? With these questions in mind, the authors eliminate the first and second step of the above design procedure, a "data-driven" approach in the sense that no traditional parametric models are used; hence, the intermediate subspace matrices, which are obtained from the process data and otherwise identified as a first step in the subspace identification methods, are used directly for the designs. Without using an explicit model, the design procedure is simplified and the modelling error caused by parameterization is eliminated. **Model Predictive Vibration Control Efficient Constrained MPC Vibration Control for Lightly Damped Mechanical Structures** Springer Science & Business Media Real-time model predictive controller (MPC) implementation in active vibration control (AVC) is often rendered difficult by fast sampling speeds and extensive actuator-deformation asymmetry. If the control of lightly damped mechanical structures is assumed, the region of attraction containing the set of allowable initial conditions requires a large prediction horizon, making the already computationally demanding on-line process even more complex. Model Predictive Vibration Control provides insight into the predictive control of lightly damped vibrating structures by exploring computationally efficient algorithms which are capable of low frequency vibration control with guaranteed stability and constraint feasibility. In addition to a theoretical primer on active vibration damping and model predictive control, Model Predictive Vibration Control provides a guide through the necessary steps in understanding the founding ideas of predictive control applied in AVC such as: · the implementation of computationally efficient algorithms · control strategies in simulation and experiment and · typical hardware requirements for piezoceramics actuated smart structures. The use of a simple laboratory model and inclusion of over 170 illustrations provides readers with clear and methodical explanations, making Model Predictive Vibration Control the ideal support material for graduates, researchers and industrial practitioners with an interest in efficient predictive control to be utilized in active vibration attenuation. **Economic Model Predictive Control Theory, Formulations and Chemical Process Applications** Springer This book presents general methods for the design of economic model predictive control (EMPC) systems for broad classes of nonlinear systems that address key theoretical and practical considerations including recursive feasibility, closed-loop stability, closed-loop performance, and computational efficiency. Specifically, the book proposes: Lyapunov-based EMPC methods for nonlinear systems; two-tier EMPC architectures that are highly computationally efficient; and EMPC schemes handling explicitly uncertainty, time-varying cost functions, time-delays and multiple-time-scale dynamics. The proposed methods employ a variety of tools ranging from nonlinear systems analysis, through Lyapunov-based control techniques to nonlinear dynamic optimization. The applicability and performance of the proposed methods are demonstrated through a number of chemical process examples. The book presents state-of-the-art methods for the design of economic model predictive control systems for chemical processes. In addition to being mathematically rigorous, these methods accommodate key practical issues, for example, direct optimization of process economics, time-varying economic cost functions and computational efficiency. Numerous comments and remarks providing fundamental understanding of the merging of process economics and feedback control into a single framework are included. A control engineer can easily tailor the many detailed examples of industrial relevance given within the text to a specific application. The authors present a rich collection of new research topics and references to significant recent work making Economic Model Predictive Control an important source of information and inspiration for academics and graduate students researching the area and for process engineers interested in applying its ideas. **Model Predictive Control** Springer Science & Business Media The second edition of "Model Predictive Control" provides a thorough introduction to theoretical and practical aspects of the most commonly used MPC strategies. It bridges the gap between the powerful but often abstract techniques of control researchers and the more empirical approach of practitioners. The book demonstrates that a powerful technique does not always require complex control algorithms. Many new exercises and examples have also been added throughout. Solutions available for download from the authors' website save the tutor time and enable the student to follow results more closely even when the tutor isn't present. **Nonlinear Model Predictive Control of Combustion Engines From Fundamentals to Applications** Springer Nature This book provides an overview of the nonlinear model predictive control (NMPC) concept for application to innovative combustion engines. Readers can use this book to become more expert in advanced combustion engine control and to develop and implement their own NMPC algorithms to solve challenging control tasks in the field. The significance of the advantages and relevancy for practice is demonstrated by real-world engine and vehicle application examples. The author provides an overview of fundamental engine control systems, and addresses emerging control problems, showing how they can be solved with NMPC. The implementation of NMPC involves various development steps, including: • reduced-order modeling of the process; • analysis of system dynamics; • formulation of the optimization problem; and • real-time feasible numerical solution of the optimization problem. Readers will see the entire process of these steps, from the fundamentals to several innovative applications. The application examples highlight the actual difficulties and advantages when implementing NMPC for engine control applications. Nonlinear Model Predictive Control of Combustion Engines targets engineers and researchers in academia and industry working in the field of engine control. The book is laid out in a structured and easy-to-read manner, supported by code examples in MATLAB®/Simulink®, thus expanding its readership to students and academics who would like to understand the fundamental concepts of NMPC. Advances in Industrial Control reports and encourages the transfer of technology in control engineering. The rapid development of control technology has an impact on all areas of the control discipline. The series offers an opportunity for researchers to present an extended exposition of new work in all aspects of industrial control. **Model Predictive Control Approaches Based on the Extended State Space Model and Extended Non-minimal State Space Model** Springer This monograph introduces the authors' work on model predictive control system design using extended state space and extended non-minimal state space approaches. It systematically describes model predictive control design for chemical processes, including the basic control algorithms, the extension to predictive functional control, constrained control, closed-loop system analysis, model predictive control optimization-based PID control, genetic algorithm optimization-based model predictive control, and industrial applications. Providing important insights, useful methods and practical algorithms that can be used in chemical process control and optimization, it offers a valuable resource for researchers, scientists and engineers in the field of process system engineering and control engineering. **Recent Advances in Model Predictive Control Theory, Algorithms, and Applications** Springer Nature This book focuses on distributed and economic Model Predictive Control (MPC) with applications in different fields. MPC is one of the most successful advanced control methodologies due to the simplicity of the basic idea (measure the current state, predict and optimize the future behavior of the plant to determine an input signal, and repeat this procedure ad infinitum) and its capability to deal with constrained nonlinear multi-input multi-output systems. While the basic idea is simple, the rigorous analysis of the MPC closed loop can be quite involved. Here, distributed means that either the computation is distributed to meet real-time requirements for (very) large-scale systems or that distributed agents act autonomously while being coupled via the constraints and/or the control objective. In the latter case, communication is necessary to maintain feasibility or to recover system-wide optimal performance. The term economic refers to general control tasks and, thus, goes beyond the typically predominant control objective of set-point stabilization. Here, recently developed concepts like (strict) dissipativity of optimal control problems or turnpike properties play a crucial role. The book collects research and survey articles on recent ideas and it provides perspectives on current trends in nonlinear model predictive control. Indeed, the book is the outcome of a series of six workshops funded by the German Research Foundation (DFG) involving early-stage career scientists from different countries and from leading European industry stakeholders. **Model Predictive Control of Wind Energy Conversion Systems** John Wiley & Sons Model Predictive Control of Wind Energy Conversion Systems addresses the predictive control strategy that has emerged as a promising digital control tool within the field of power electronics, variable-speed motor drives, and energy conversion systems. The authors provide a comprehensive analysis on the model predictive control of power converters employed in a wide variety of variable-speed wind energy conversion systems (WECS). The contents of this book includes an overview of wind energy system configurations, power converters for variable-speed WECS, digital control techniques, MPC, modeling of power converters and wind generators for MPC design. Other topics include the mapping of continuous-time models to discrete-time models by various exact, approximate, and quasi-exact discretization methods, modeling and control of wind turbine grid-side two-level and multilevel voltage source converters. The authors also focus on the MPC of several power converter configurations for full variable-speed permanent magnet synchronous generator based WECS, squirrel-cage induction generator based WECS, and semi-variable-speed doubly fed induction generator based WECS. Furthermore, this book: Analyzes a wide variety of practical WECS, illustrating important concepts with case studies, simulations, and experimental results Provides a step-by-step design procedure for the development of predictive control schemes for various WECS configurations Describes continuous- and discrete-time modeling of wind generators and power converters, weighting factor selection, discretization methods, and extrapolation techniques Presents useful material for other power electronic applications such as variable-speed motor drives, power quality conditioners, electric vehicles, photovoltaic energy systems, distributed generation, and high-voltage direct current transmission. Explores S-Function Builder programming in MATLAB environment to implement various MPC strategies through the companion website Reflecting the latest technologies in the field, Model Predictive Control of Wind Energy Conversion Systems is a valuable reference for academic researchers, practicing engineers, and other professionals. It can also be used as a textbook for graduate-level and advanced undergraduate courses. **Explicit Nonlinear Model Predictive Control Theory and Applications** Springer Nonlinear Model Predictive Control (NMPC) has become the accepted methodology to solve complex control problems related to process industries. The main motivation behind explicit NMPC is that an explicit state feedback law avoids the need for executing a numerical optimization algorithm in real time. The benefits of an explicit solution, in addition to the efficient on-line computations, include also verifiability of the implementation and the possibility to design embedded control systems with low software and hardware complexity. This book considers the multi-parametric Nonlinear Programming (mp-NLP) approaches to explicit approximate NMPC of constrained nonlinear systems, developed by the authors, as well as their applications to various NMPC problem formulations and several case studies. The following types of nonlinear systems are considered, resulting in different NMPC problem formulations: □ Nonlinear systems described by first-principles models and nonlinear systems described by black-box models; - Nonlinear systems with continuous control inputs and nonlinear systems with quantized control inputs; - Nonlinear systems without uncertainty and nonlinear systems with uncertainties (polyhedral description of uncertainty and stochastic description of uncertainty); - Nonlinear systems, consisting of interconnected nonlinear sub-systems. The proposed mp-NLP approaches are illustrated with applications to several case studies, which are taken from diverse areas such as automotive mechatronics, compressor control, combustion plant control, reactor control, pH maintaining system control, cart and spring system control, and diving computers. **Distributed Model Predictive Control for Plant-Wide Systems** John Wiley & Sons A comprehensive examination of DMPC theory and its technological applications • A comprehensive examination of DMPC theory and its technological applications from basic through to advanced level • A systematic introduction to DMPC technology providing classic DMPC coordination strategies, analysis of their performance, and design methods for both unconstrained and constrained systems • Includes the system partition methods, coordination strategies, the performance analysis and how to design stabilized DMPC under different coordination strategies • Presents useful theories and technologies which can be used in many different industrial fields, such as the metallurgical process and high speed transport, helping readers to grasp the procedure of using the DMPC • Reflects the authors' combined research in the area, providing a wealth of and current and background information **Assessment and Future Directions of Nonlinear Model Predictive Control** Springer The past three decades have seen rapid development in the area of model predictive control with respect to both theoretical and application aspects. Over these 30 years, model predictive control for linear systems has

been widely applied, especially in the area of process control. However, today's applications often require driving the process over a wide region and close to the boundaries of - erability, while satisfying constraints and achieving near-optimal performance. Consequently, the application of linear control methods does not always lead to satisfactory performance, and here nonlinear methods must be employed. This is one of the reasons why nonlinear model predictive control (NMPC) has - joyed signi?cant attention over the past years, with a number of recent advances on both the theoretical and application frontier. Additionally, the widespread availability and steadily increasing power of today's computers, as well as the development of specially tailored numerical solution methods for NMPC, bring the practical applicability of NMPC within reach even for very fast systems. This has led to a series of new, exciting developments, along with new challenges in the area of NMPC. **Advanced Model Predictive Control** "Model predictive control is an advanced method of process control that has been in use in the process industries in chemical plants and oil refineries since the 1980s. In recent years it has also been used in power system balancing models. Model predictive controllers rely on dynamic models of the process, most often linear empirical models obtained by system identification. The main advantage of model predictive control is the fact that it allows the current timeslot to be optimized, while keeping future timeslots in account. This is achieved by optimizing a finite time-horizon, but only implementing the current timeslot. Model predictive control has the ability to anticipate future events and can take control actions accordingly. MPC models predict the change in the dependent variables of the modelled system that will be caused by changes in the independent variables. In a chemical process, independent variables that can be adjusted by the controller are often either the setpoints of regulatory PID controllers or the final control element. Independent variables that cannot be adjusted by the controller are used as disturbances. Dependent variables in these processes are other measurements that represent either control objectives or process constraints. The book entitled *Advanced Model Predictive Control* is intended to present the readers the recent achievements in this field. The book also delivers applications of MPC in modern industry and effective commercial software for MPC is familiarized." **Model Predictive Control System Design and Implementation Using MATLAB®** Springer Science & Business Media *Model Predictive Control System Design and Implementation Using MATLAB®* proposes methods for design and implementation of MPC systems using basis functions that confer the following advantages: - continuous- and discrete-time MPC problems solved in similar design frameworks; - a parsimonious parametric representation of the control trajectory gives rise to computationally efficient algorithms and better on-line performance; and - a more general discrete-time representation of MPC design that becomes identical to the traditional approach for an appropriate choice of parameters. After the theoretical presentation, coverage is given to three industrial applications. The subject of quadratic programming, often associated with the core optimization algorithms of MPC is also introduced and explained. The technical contents of this book is mainly based on advances in MPC using state-space models and basis functions. This volume includes numerous analytical examples and problems and MATLAB® programs and exercises. **Introduction to Model Predictive Control With Matlab** Createspace Independent Publishing Platform *Model Predictive Control Toolbox* provides functions, an app, and Simulink blocks for designing and simulating model predictive controllers (MPCs). The toolbox lets you specify plant and disturbance models, horizons, constraints, and weights. By running closed-loop simulations, you can evaluate controller performance. You can adjust the behavior of the controller by varying its weights and constraints at run time. To control a nonlinear plant, you can implement adaptive and gain-scheduled MPCs. For applications with fast sample rates, you can generate an explicit model predictive controller from a regular controller or implement an approximate solution. For rapid prototyping and embedded system implementation, the toolbox supports automatic C-code and Structured Text generation. The most important content that this book provides are the following: -MPC Modeling -Plant Model -Disturbance Model -Measurement Noise Model -Signal Types, Inputs and Outputs -Construct Linear Time Invariant (LTI) Models -Transfer Function Models -Zero/Pole/Gain Models -State-Space Models -LTI Object Properties -LTI Model Characteristics -Specify Multi-Input Multi-Output Plants -CSTR Model -Linearize Simulink Models -Linearization Using MATLAB Code -Linearization Using Linear Analysis Tool in Simulink Control Design -Linearize Simulink Models Using MPC Designer -Define MPC Structure By Linearization -Linearize Model -Specifying Operating Points -Connect Measured Disturbances for Linearization -Identify Plant from Data -Identify Plant from Data at the Command Line -Working with Impulse-Response Models -Design MPC Controller for Identified Plant Model -Design Controller for Identified Plant Using Apps -Design Controller for Identified Plant at the Command Line -Configure Noise Channels as Unmeasured Disturbances -Design Controller Using MPC Designer -Test Controller Robustness -Design MPC Controller for Plant with Delays -Design MPC Controller for Nonsquare Plant -Design MPC Controller at the Command Line -Simulate Controller with Nonlinear Plant -Nonlinear CSTR Application -Example Code for Successive Linearization -CSTR Results and Discussion -Compute Steady-State Gain -Extract Controller -Signal Previewing -Update Constraints at Run Time -Update Bounds on Input and Output Signals at Run Time -Update Custom Linear Constraints at Run Time -Tune Weights at Run Time -Designing and Testing Controllers in Simulink -Design MPC Controller in Simulink -Test an Existing Controller **Model Predictive Control of High Power Converters and Industrial Drives** John Wiley & Sons In this original book on model predictive control (MPC) for power electronics, the focus is put on high-power applications with multilevel converters operating at switching frequencies well below 1 kHz, such as medium-voltage drives and modular multi-level converters. Consisting of two main parts, the first offers a detailed review of three-phase power electronics, electrical machines, carrier-based pulse width modulation, optimized pulse patterns, state-of-the art converter control methods and the principle of MPC. The second part is an in-depth treatment of MPC methods that fully exploit the performance potential of high-power converters. These control methods combine the fast control responses of deadbeat control with the optimal steady-state performance of optimized pulse patterns by resolving the antagonism between the two. MPC is expected to evolve into the control method of choice for power electronic systems operating at low pulse numbers with multiple coupled variables and tight operating constraints it. *Model Predictive Control of High Power Converters and Industrial Drives* will enable to reader to learn how to increase the power capability of the converter, lower the current distortions, reduce the filter size, achieve very fast transient responses and ensure the reliable operation within safe operating area constraints. Targeted at power electronic practitioners working on control-related aspects as well as control engineers, the material is intuitively accessible, and the mathematical formulations are augmented by illustrations, simple examples and a book companion website featuring animations. Readers benefit from a concise and comprehensive treatment of MPC for industrial power electronics, enabling them to understand, implement and advance the field of high-performance MPC schemes. **Advanced Model Predictive Control** IntechOpen *Model Predictive Control (MPC)* refers to a class of control algorithms in which a dynamic process model is used to predict and optimize process performance. From lower request of modeling accuracy and robustness to complicated process plants, MPC has been widely accepted in many practical fields. As the guide for researchers and engineers all over the world concerned with the latest developments of MPC, the purpose of "Advanced Model Predictive Control" is to show the readers the recent achievements in this area. The first part of this exciting book will help you comprehend the frontiers in theoretical research of MPC, such as Fast MPC, Nonlinear MPC, Distributed MPC, Multi-Dimensional MPC and Fuzzy-Neural MPC. In the second part, several excellent applications of MPC in modern industry are proposed and efficient commercial software for MPC is introduced. Because of its special industrial origin, we believe that MPC will remain energetic in the future. **Frontiers of Model Predictive Control** BoD – Books on Demand *Model Predictive Control (MPC)* usually refers to a class of control algorithms in which a dynamic process model is used to predict and optimize process performance, but it is can also be seen as a term denoting a natural control strategy that matches the human thought form most closely. Half a century after its birth, it has been widely accepted in many engineering fields and has brought much benefit to us. The purpose of the book is to show the recent advancements of MPC to the readers, both in theory and in engineering. The idea was to offer guidance to researchers and engineers who are interested in the frontiers of MPC. The examples provided in the first part of this exciting collection will help you comprehend some typical boundaries in theoretical research of MPC. In the second part of the book, some excellent applications of MPC in modern engineering field are presented. With the rapid development of modeling and computational technology, we believe that MPC will remain as energetic in the future. **Model Predictive Control Theory and Design** Nob Hill Pub, Llc **Model Predictive Control for Constrained Nonlinear Systems** vdf Hochschulverlag AG **Nonlinear Model Predictive Control Theory and Algorithms** Springer Science & Business Media *Nonlinear Model Predictive Control* is a thorough and rigorous introduction to nonlinear model predictive control (NMPC) for discrete-time and sampled-data systems. NMPC is interpreted as an approximation of infinite-horizon optimal control so that important properties like closed-loop stability, inverse optimality and suboptimality can be derived in a uniform manner. These results are complemented by discussions of feasibility and robustness. NMPC schemes with and without stabilizing terminal constraints are detailed and intuitive examples illustrate the performance of different NMPC variants. An introduction to nonlinear optimal control algorithms gives insight into how the nonlinear optimisation routine – the core of any NMPC controller – works. An appendix covering NMPC software and accompanying software in MATLAB® and C++ (downloadable from www.springer.com/ISBN) enables readers to perform computer experiments exploring the possibilities and limitations of NMPC. **Model Predictive Control Theory, Practices and Future Challenges** Although industrial processes are inherently nonlinear, many contributions for controller design for those plants are based on the assumption of a linear model of the system. However, in some cases it is difficult to represent a given process using a linear model. *Model Predictive Control (MPC)* is an optimal control approach which can effectively deal with constraints and multivariable processes in industries. Because of its advantages, MPC has been widely applied in automotive and process control communities. This book discusses the theory, practices and future challenges of model predictive control. **Model Predictive Control Theory, Practices and Future Challenges** Nova Science Pub Incorporated Although industrial processes are inherently nonlinear, many contributions for controller design for those plants are based on the assumption of a linear model of the system. However, in some cases it is difficult to represent a given process using a linear model. *Model Predictive Control (MPC)* is an optimal control approach which can effectively deal with constraints and multivariable processes in industries. Because of its advantages, MPC has been widely applied in automotive and process control communities. This book discusses the theory, practices and future challenges of model predictive control. **A First Course in Predictive Control** CRC Press The book presents a significant expansion in depth and breadth of the previous edition. It includes substantially more numerical illustrations and copious supporting MATLAB code that the reader can use to replicate illustrations or build his or her own. The code is deliberately written to be as simple as possible and easy to edit. The book is an excellent starting point for any researcher to gain a solid grounding in MPC concepts and algorithms before moving into application or more advanced research topics. Sample problems for readers are embedded throughout the chapters, and in-text questions are designed for readers to demonstrate an understanding of concepts through numerical simulation. **Computationally Efficient Model Predictive Control Algorithms A Neural Network Approach** Springer Science & Business Media This book thoroughly discusses computationally efficient (suboptimal) *Model Predictive Control (MPC)* techniques based on neural models. The subjects treated include: · A few types of suboptimal MPC algorithms in which a linear approximation of the model or of the predicted trajectory is successively calculated on-line and used for prediction. · Implementation details of the MPC algorithms for feed forward perceptron neural models, neural Hammerstein models, neural Wiener models and state-space neural models. · The MPC algorithms based on neural multi-models (inspired by the idea of predictive control). · The MPC algorithms with neural approximation with no on-line linearization. · The MPC algorithms with guaranteed stability and robustness. · Cooperation between the MPC algorithms and set-point optimization. Thanks to linearization (or neural approximation), the presented suboptimal algorithms do not require demanding on-line nonlinear optimization. The presented simulation results demonstrate high accuracy and computational efficiency of the algorithms. For a few representative nonlinear benchmark processes, such as chemical reactors and a distillation column, for which the classical MPC algorithms based on linear models do not work properly, the trajectories obtained in the suboptimal MPC algorithms are very similar to those given by the "ideal" MPC algorithm with on-line nonlinear optimization repeated at each sampling instant. At the same time, the suboptimal MPC algorithms are significantly less computationally demanding. **Model Predictive Control on Open Water Systems** IOS Press "In the research *Model Predictive Control on Open Water Systems*, the relatively new control methodology *Model Predictive Control* is configured for application of water quantity control on open water systems, especially on irrigation canals and large drainage systems. The methodology applies an internal model of the open water system, by which optimal control actions are calculated over a prediction horizon. As internal model, two simplified models are used, the Integrator Delay model and the Saint Venant model. Kalman filtering is applied to initialize the internal models. The optimization uses an objective function in which conflicting objectives can be weighed. In most of the cases, these conflicting objectives are keeping the water levels at different locations in the water system within a range around setpoint and executing this by using as little control effort or energy as possible. To tune the weight factors in the objective function, an estimate of the maximum allowed value of each variable in the objective function is used. The optimization takes the constraints of the control structures into account. Every control time step, the optimal control actions are calculated, while only the first set of control actions is actually executed. This results in a controlled water system that is constantly maintaining the objective in an optimal way, while taking predictions, such as expected irrigation demands or extreme storm events and the constraints of the water system into account." **Model Predictive Control Handbook** This book provides elucidative information regarding *Model Predictive Control (MPC)*. *Model predictive control* is that part of control algorithms in which a progressive method structure is utilized to foretell and improve process work. Also, it can be viewed as an expression demonstrating a typical restrain scheme that replicates the human thinking capability most efficiently. Nearly 50

years after its origin, it is vastly being welcomed in lot of spheres of engineering and is proving to be very advantageous. The book focuses on the latest developments in the field of MPC, in practice and theory, and structured in a way to provide in-depth knowledge to the practitioners and discoverers who want to gain information about the perimeters of MPC research. The book deals with the limits of MPC in theory and provides enough examples to enable us to understand them. It also portrays the practical usage of MPC in recent engineering spheres. As analytical and structural technology is growing rapidly, MPC will remain at the forefront even in the future.